

RGB-D and Thermal data for Human Analysis

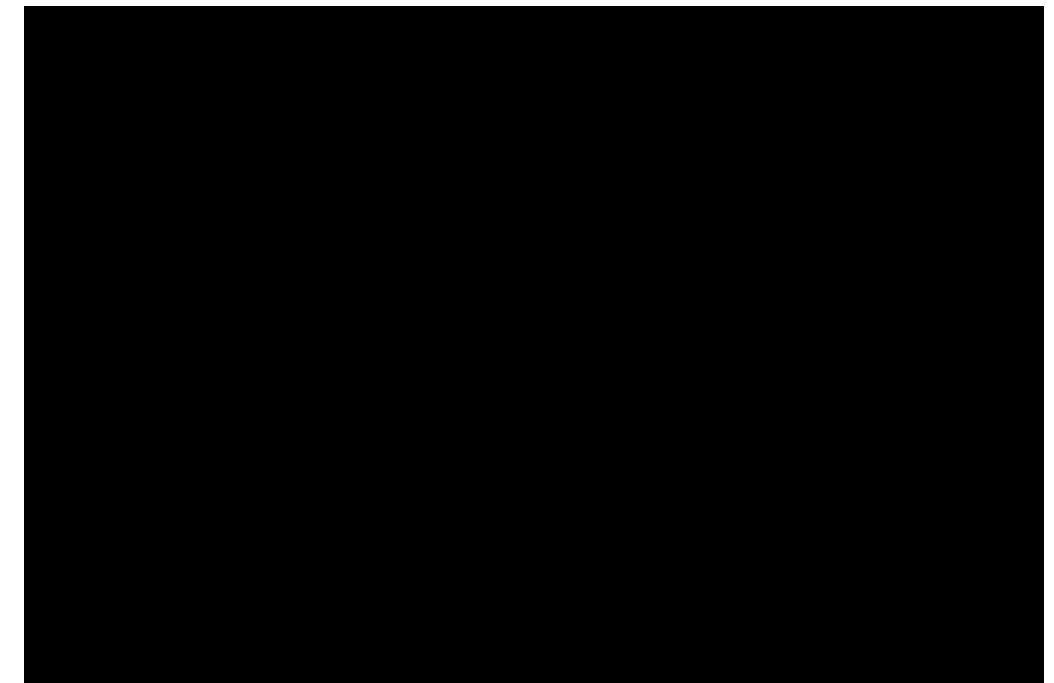
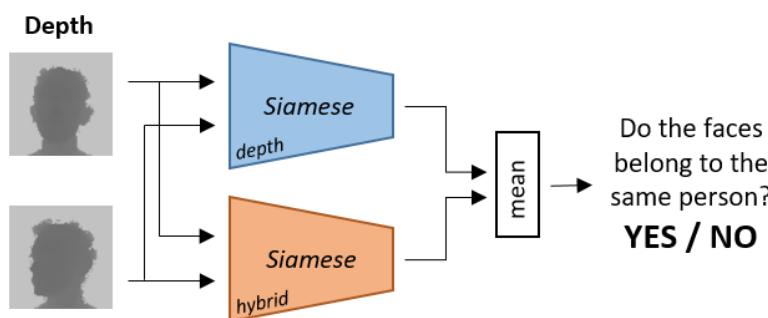
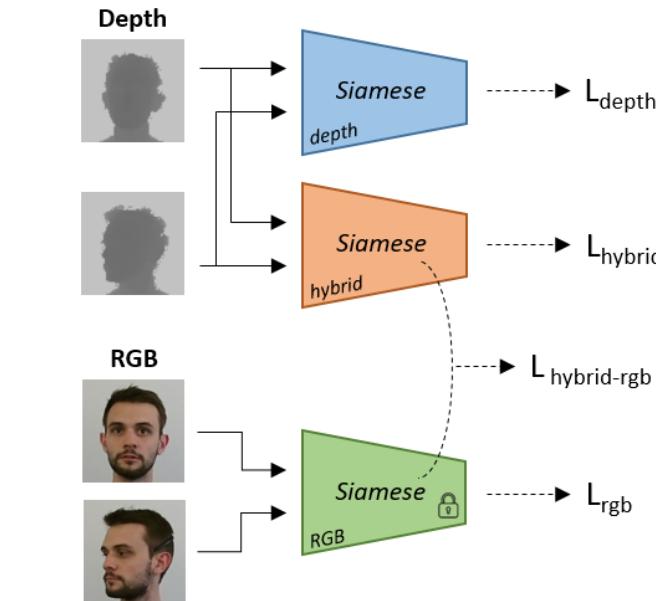


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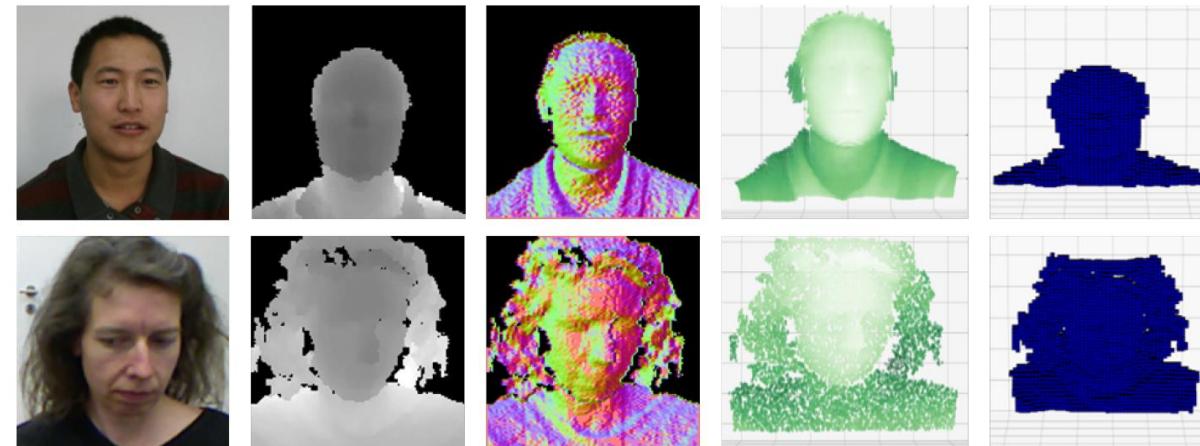
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Face Verification using Privileged Information



Which is the most effective representation of depth maps for the face recognition task?
Which kind of neural networks should be used to analyze them?



Findings:

- Huge discrepancy between intra- and cross-dataset experiments and between different sensor-subject distances
- Surface normals and point clouds obtain the higher recognition accuracy in cross-dataset experiments

MultiSFace

A multi-sensor dataset for Face Recognition

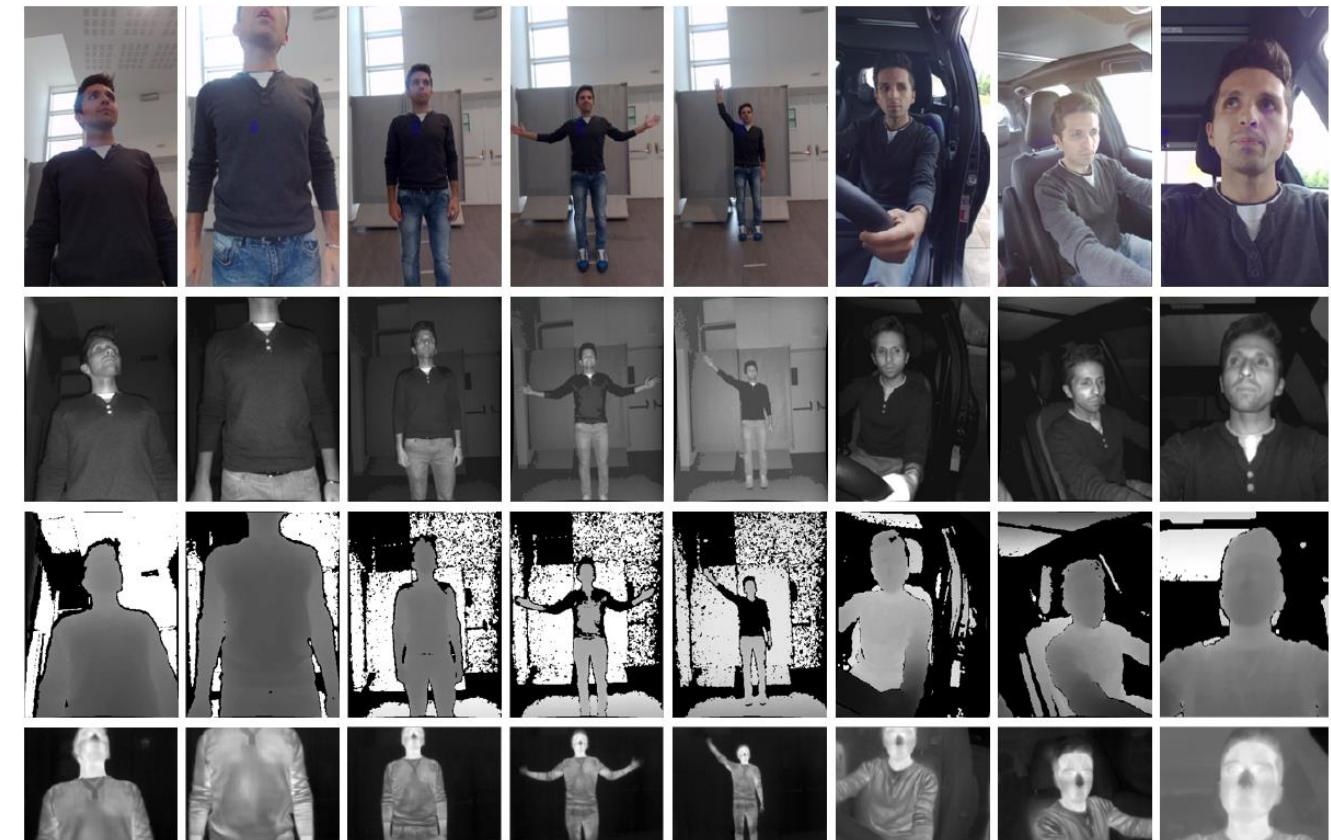
- 31 subjects
- 3 different poses (frontal, side, and back)
- 2 different distances (1m, 2.5m)
- Multiple synchronized devices:
 - Depth (ToF):
 - Pico Zense DCAM7101 (high res)
 - Pmdtec Pico Flexx 2 (low res)
 - Thermal:
 - Flir Boson 640 (high res)
 - Flir PureThermal 2 with Flir Letpon 3.5 (low res, radiometric)
 - RGB



Baracca Dataset

A multi-sensor dataset for the estimation of anthropometric measurements and soft biometrics

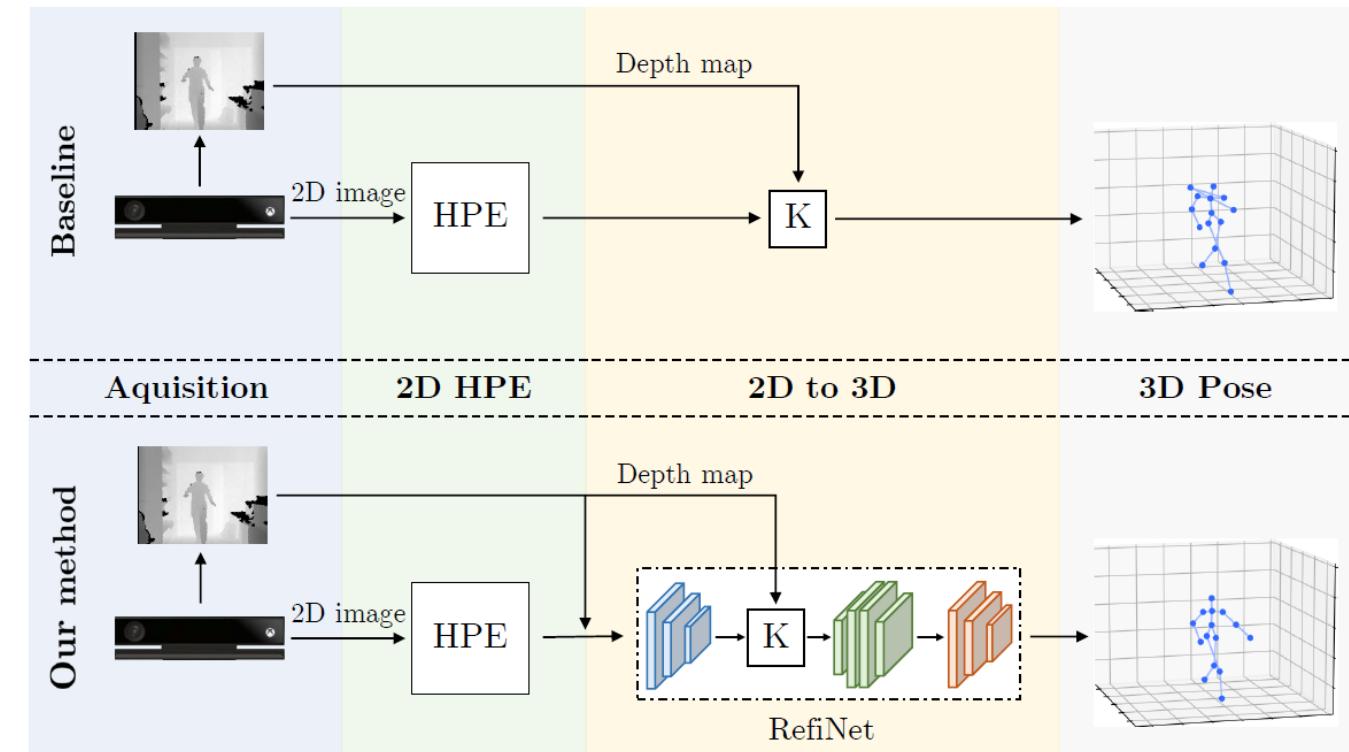
- 30 subjects
- 5 in-car sequences
- 3 outdoor sequences
- Two synchronized devices:
 - Pico Zense DCAM7101 (ToF, RGB+IR+DEPTH)
 - Flir PureThermal 2 with Flir Letpon 3.5 (radiometric thermal sensor)
- Anthropometric measurements:
height, shoulder width, forearm and arm length, torso width, leg length, eye height from the ground.
- Soft-biometric traits: age, sex, weight



1. S. Pini, A. D'Eusanio, G. Borghi, R. Vezzani, R. Cucchiara, Baracca: a Multimodal Dataset for Anthropometric Measurements in Automotive, to appear in IJCB 2020
2. A. D'Eusanio, S. Pini, G. Borghi, R. Vezzani, R. Cucchiara, RefiNet: 3D Human Pose Refinement with Depth Maps, to appear in ICPR 2020

RefiNet: 3D Human Pose Refinement with Depth Maps

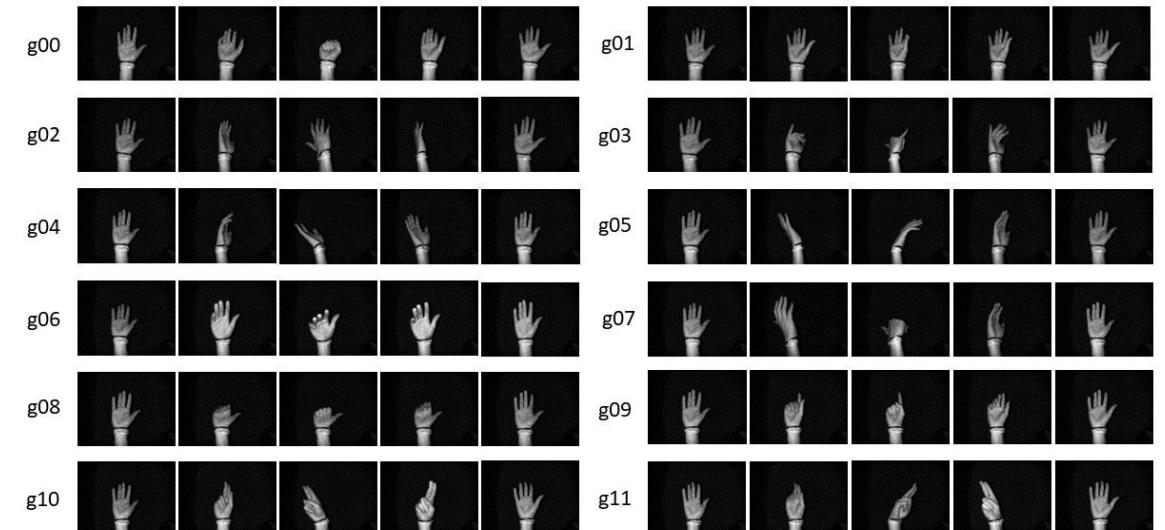
- Goal: Obtain accurate 3D human pose estimation (in the camera space) from RGB-D data (ToF sensors) and an estimated 2D pose
- Steps:
 - 2D HPE
 - 2D joint refinement
 - From 2D to 3D pose using depth maps and camera calibration parameters
 - 3D joint refinement
 - 3D pose refinement



A dynamic hand gesture dataset for the Human-Car Interaction

- 40 subjects
- 12 gestures
- Each gesture is repeated three times
- Multiple devices:
 - Depth (ToF):
 - Pmdtec Pico Flexx (Depth+IR)
 - Stereo InfraRed:
 - Leap Motion (IR+3D hand joints)
 - RGB

Briareo Dataset



Thank you! Questions?

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